

EP50S Series

Diameter ϕ 50mm Shaft type Absolute Rotary encoder

■ Features

- Compact size of external diameter ϕ 50mm
- Various output code: BCD, Binary, Gray code (Customizable)
- Various and high resolution (720, 1024 divisions)
- Protection structure IP64 (Dust-proof, Oil-proof)



■ Applications

Precision machine tool, Fabric machinery, Robot, Parking system



Please read "Caution for your safety" in operation manual before using.



■ Ordering information

EP50S	8	-	1024	-	1	R	-	P	-	24
Series	Shaft diameter	Pulse/1Revolution	Output code		Revolution direction		Control output		Power supply	
Diameter ϕ 50mm shaft type	ϕ 8mm	Refer to resolution	1 : BCD Code 2 : Binary Code 3 : Gray Code	F : Output value increase at CW direction R : Output value increase at CCW direction	P : PNP open collector output N : NPN open collector output	5 : 5VDC \pm 5% 24 : 12~24VDC \pm 5%				

*Gray code is customizable.

■ Specifications

Item		Diameter ϕ 50mm shaft type of absolute rotary encoder								
Resolution		(Note1) 6, 8, 10, 12, 16, 20, 24, 32, 40, 45, 48, 64, 90, 128, 180, 256, 360, 512, 720, 1024 division								
Electrical specification	Output code	BCD Code	Binary Code	Gray Code		BCD Code	Binary Code	Gray Code		
	1024 division	TS:0.3515° \pm 15' (1.3bit)	TS:0.3515° \pm 15' (10bit)	TS:0.703° \pm 15' (10bit)		TP1:12° \pm 60'(1bit)	TP1:12° \pm 60'(1bit)	TP1:12° \pm 60'(1bit)		
	720 division	TS:0.5° \pm 25' (11bit)	TS:0.5° \pm 25' (10bit)	TS:1° \pm 25' (10bit)		TP2:2° \pm 60'(1bit)	TP2:2° \pm 60'(1bit)	TP2:2° \pm 60'(1bit)		
	512 division	TS:0.703° \pm 15' (11bit)	TS:0.703° \pm 15' (9bit)	TS:1.406° \pm 15' (9bit)		TS:18° \pm 60'(5bit)	TS:18° \pm 60'(5bit)	TS:36° \pm 60'(5bit)		
	360 division	TS:1° \pm 25'(10bit)	TS:1° \pm 25'(9bit)	TS:2° \pm 25'(9bit)		EP:18° \pm 60'(1bit)	EP:18° \pm 60'(1bit)	EP:18° \pm 60'(1bit)		
	256 division	TS:1.406° \pm 15' (10bit)	TS:1.406° \pm 15' (8bit)	TS:2.8125° \pm 15' (8bit)		TP1:15° \pm 60'(1bit)	TP1:15° \pm 60'(1bit)	TP1:15° \pm 60'(1bit)		
	180 division	TS:2° \pm 25'(9bit)	TS:2° \pm 25'(8bit)	TS:4° \pm 25'(8bit)		TP2:2° \pm 60'(1bit)	TP2:2° \pm 60'(1bit)	TP2:2° \pm 60'(1bit)		
	128 division	TS:2.8125° \pm 15' (9bit)	TS:2.8125° \pm 15' (7bit)	TS:5.625° \pm 15' (7bit)		TS:22.5° \pm 60' (5bit)	TS:22.5° \pm 60' (4bit)	TS:45° \pm 60'(4bit)		
	90 division	TS:4° \pm 25'(8bit)	TS:4° \pm 25'(7bit)	TS:8° \pm 25'(7bit)		EP:22.5° \pm 60' (1bit)	EP:22.5° \pm 60' (1bit)	EP:45° \pm 60' (1bit)		
	64 division	TS:5.625° \pm 15' (7bit)	TS:5.625° \pm 15' (6bit)	TS:11.25° \pm 15' (6bit)		TP1:15° \pm 60'(1bit)	TP1:15° \pm 60'(1bit)	TP1:15° \pm 60'(1bit)		
	48 division	TS:7.5° \pm 25'(7bit)	TS:7.5° \pm 25'(6bit)	TS:15° \pm 25'(6bit)		TP2:3° \pm 60'(1bit)	TP2:3° \pm 60'(1bit)	TP2:3° \pm 60'(1bit)		
	45 division	TS:8° \pm 25'(7bit)	TS:8° \pm 25'(6bit)	TS:16° \pm 25'(6bit)		TS:30° \pm 60'(5bit)	TS:30° \pm 60'(4bit)	TS:60° \pm 60'(4bit)		
	40 division	TP1:5° \pm 60'(1bit) TP2:2° \pm 60'(1bit) TS:9° \pm 60'(6bit) EP:9° \pm 60'(1bit)	TP1:5° \pm 60'(1bit) TP2:2° \pm 60'(1bit) TS:9° \pm 60'(6bit) EP:9° \pm 60'(1bit)	TP1:5° \pm 60'(1bit) TP2:2° \pm 60'(1bit) TS:18° \pm 60'(6bit) EP:9° \pm 60'(1bit)		TP1:30° \pm 60'(1bit)	TP1:30° \pm 60'(1bit)	TP1:30° \pm 60'(1bit)		
	32 division	TP1:7° \pm 60'(1bit) TP2:2° \pm 60'(1bit) TS:11.25° \pm 60' (6bit) EP:11.25° \pm 60' (1bit)	TP1:7° \pm 60'(1bit) TP2:2° \pm 60'(1bit) TS:11.25° \pm 60' (5bit) EP:11.25° \pm 60' (1bit)	TP1:7° \pm 60'(1bit) TP2:2° \pm 60'(1bit) TS:22.5° \pm 60' (3bit) EP:11.25° \pm 60' (1bit)		TP1:39° \pm 60'(1bit)	TP1:39° \pm 60'(1bit)	TP1:39° \pm 60'(1bit)		
	24 division	TP1:8° \pm 60'(1bit) TP2:3° \pm 60'(1bit) TS:15° \pm 60'(6bit) EP:15° \pm 60'(1bit)	TP1:8° \pm 60'(1bit) TP2:3° \pm 60'(1bit) TS:15° \pm 60'(5bit) EP:15° \pm 60'(1bit)	TP1:8° \pm 60'(1bit) TP2:3° \pm 60'(1bit) TS:30° \pm 60'(5bit) EP:15° \pm 60'(1bit)		TP1:53° \pm 60'(1bit)	TP1:53° \pm 60'(1bit)	TP1:53° \pm 60'(1bit)		
	Control output	Output voltage : Min. (Power supply - 1.5)VDC, Load current : Max. 32mA								
	NPN open collector output	Load current : Max. 32mA, Residual voltage : Max. 1VDC								
Response time(Rise/Fall)		Ton=800nsec, Toff=Max. 800nsec(Cable length : 2m, I sink=32mA)								
Max. Response frequency		35kHz								
Power supply		• 5VDC \pm 5% (Ripple P-P : Max. 5%) • 12~24VDC \pm 5% (Ripple P-P : Max. 5%)								
Current consumption		Max. 100mA (disconnection of the load)								
Insulation resistance		Min. 100M Ω (at 500VDC megger between all terminals and case)								
Dielectric strength		750VAC 50/60Hz for 1 minute (Between all terminals and case)								
Connection		Cable outgoing type (Cable gland)								

* (Note1) Not indicated type is customizable.

* (Note2) TS=Signal Pulse, TP=Timing Pulse, EP=Even Parity

Ø 50mm Shaft Absolute Type

■ Specifications

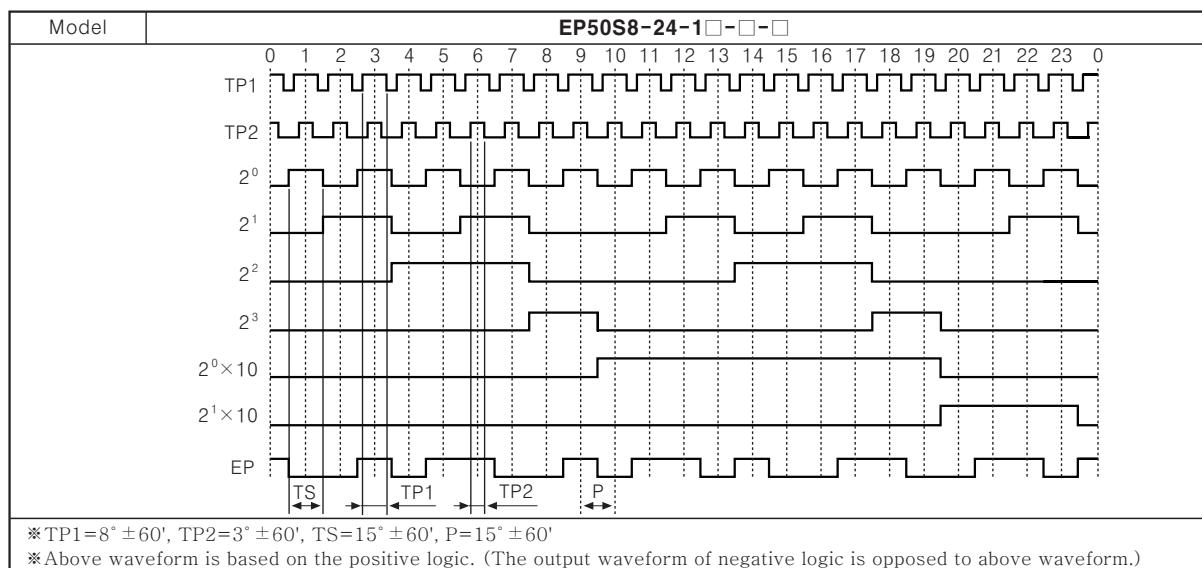
Item	Diameter Ø 50mm shaft type of absolute rotary encoder	
Mechanical specification	Starting torque	Max. 40gf · cm(0.004N · m)
	Moment of inertia	Max. 40g · cm ² (4 × 10 ⁻⁶ kg · m ²)
	Shaft loading	Radial : 10kgf, Thrust : 2.5kgf
	Max. allowable revolution	(Note2) 3000rpm
Vibration	1.5mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 2 hours	
Shock	Max. 50G	
Ambient temperature	−10 to 70°C(at non-freezing status), Storage : −25 to 85°C	
Ambient humidity	35 to 85%RH, Storage: 35 to 90%RH	
Protection	IP64 (IEC standard)	
Cable	Ø 7mm, 15P, Length : 2m, Shield cable (AWG 28, Core wire diameter: 0.08mm, No. of core wire: 40, Insulator out diameter: 0.8mm)	
Accessory	Fixing bracket, Coupling	
Approval	CE	
Unit weight	Approx. 380g	

* (Note3) Max. allowable revolution ≥ Max. response revolution [Max. response revolution(rpm) = $\frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec.}$]

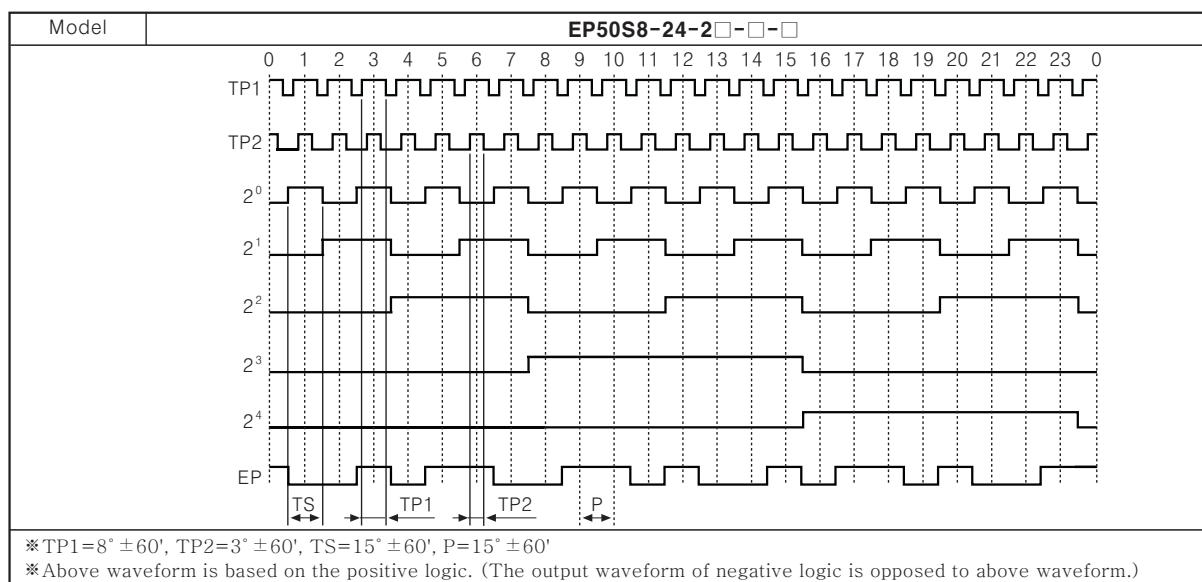
Make sure that max. response revolution should be lower than max. allowable revolution when selecting the resolution.

■ Output waveform

● 24 division (BCD CODE output)



● 24 division (BINARY CODE output)

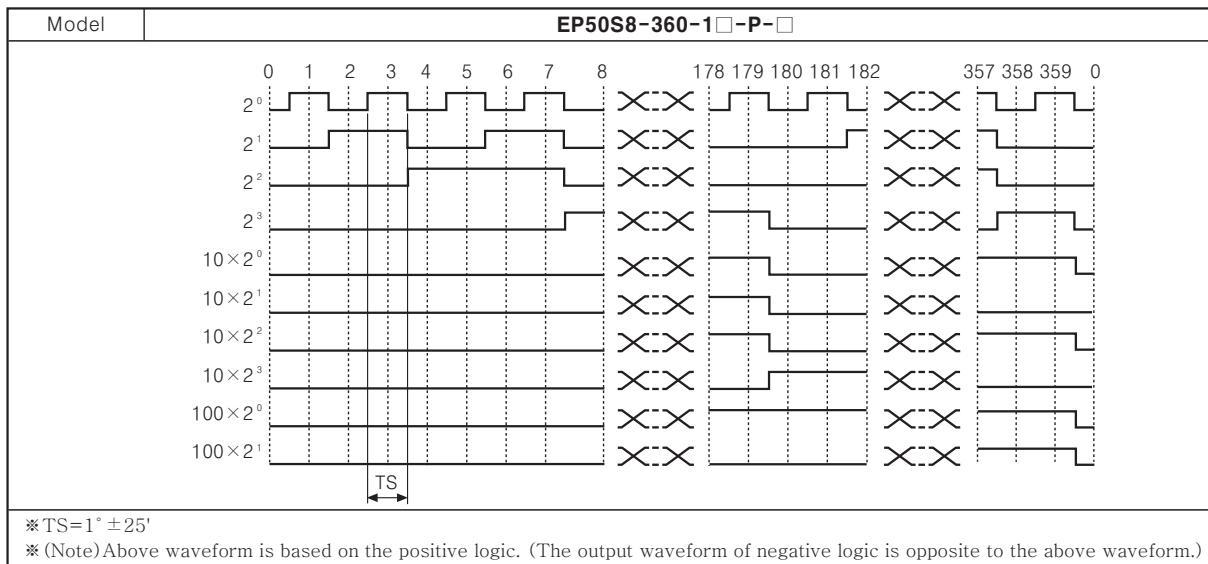


- (A) Photo electric sensor
- (B) Fiber optic sensor
- (C) Door/Area sensor
- (D) Proximity sensor
- (E) Pressure sensor
- (F) Rotary encoder
- (G) Connector/Socket
- (H) Temp. controller
- (I) SSR/Power controller
- (J) Counter
- (K) Timer
- (L) Panel meter
- (M) Tacho/Speed/Pulse meter
- (N) Display unit
- (O) Sensor controller
- (P) Switching power supply
- (Q) Stepping motor & Driver & Controller
- (R) Graphic/Logic panel
- (S) Field network device
- (T) Production stoppage models & replacement

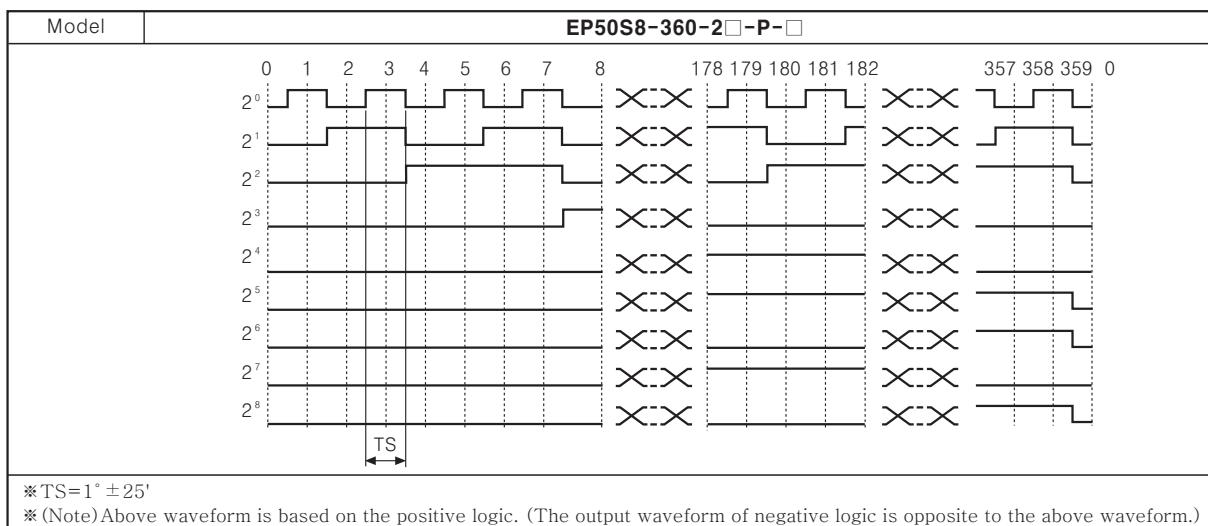
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□ Output waveform

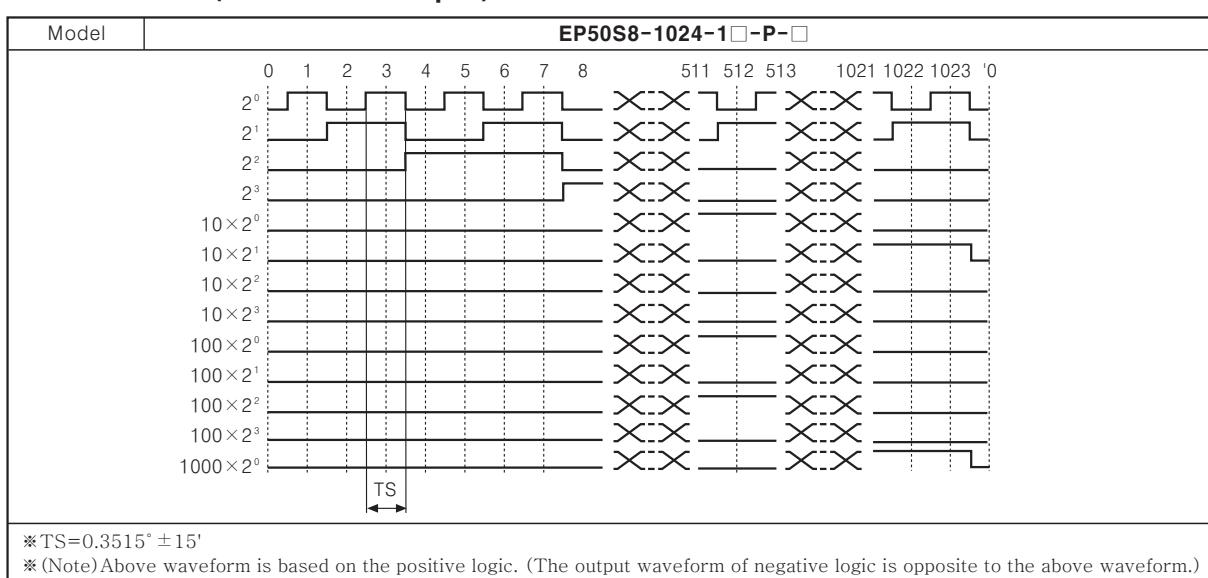
● 360 division (BCD CODE output)



● 360 division (BINARY CODE output)



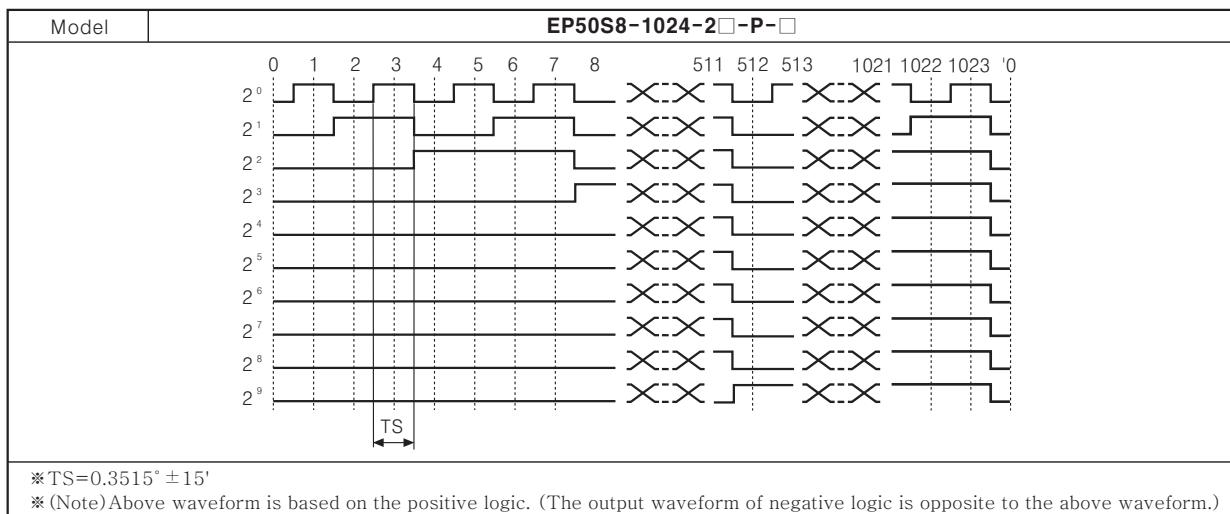
● 1024 division (BCD CODE output)



Ø 50mm Shaft Absolute Type

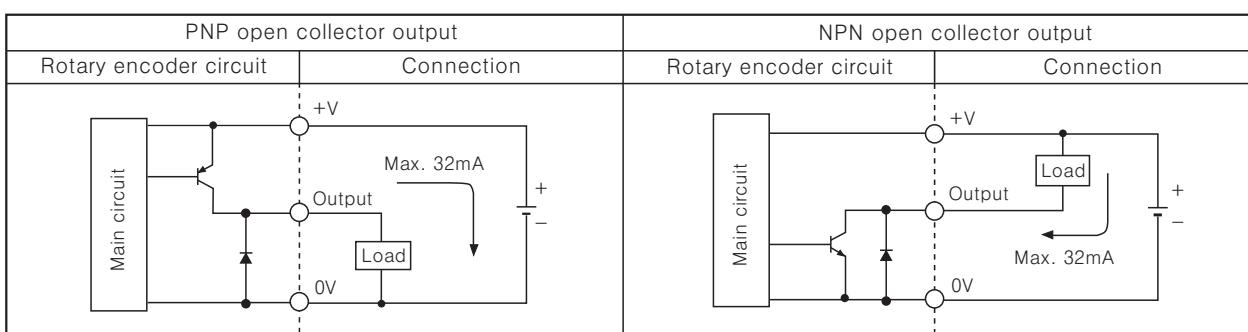
■ Output waveform

● 1024 division (BINARY CODE output)



- (A) Photo electric sensor
- (B) Fiber optic sensor
- (C) Door/Area sensor
- (D) Proximity sensor
- (E) Pressure sensor
- (F) Rotary encoder
- (G) Connector/Socket
- (H) Temp. controller
- (I) SSR/Power controller
- (J) Counter
- (K) Timer
- (L) Panel meter
- (M) Tacho/Speed/Pulse meter
- (N) Display unit
- (O) Sensor controller
- (P) Switching power supply
- (Q) Stepping motor & Driver & Controller
- (R) Graphic/Logic panel
- (S) Field network device
- (T) Production stoppage models & replacement

■ Control output diagram



※ Output circuits of all phases are the same.

■ Connections

● BCD Code

Resolution	6 division	8 division	10 division	12 division	16 division	20 division	24 division	32 division	40 division	45 division	48 division	64 division	90 division	128 division	180 division	256 division	360 division	512 division	720 division	1024 division
Color	White																			
Power	White																+V			
	Boack																0V			
	Brown																2 ⁰			
	Red																2 ¹			
	Orange																2 ²			
	Yellow	N.C.															2 ³			
	Blue	N.C.															2 ⁰ × 10			
Output wire	Purple		N.C.														2 ¹ × 10			
	Gray		N.C.														2 ² × 10			
	White/Brown			TP1						N.C.							2 ³ × 10			
	White/Red			TP2						N.C.							2 ⁰ × 100			
	White/Orange			EP						N.C.							2 ¹ × 100			
	White/Yellow				N.C.												2 ² × 100			
	White/Blue					N.C.											2 ³ × 100			
	White/Purple					N.C.											2 ⁰ × 1000			
	Shield wire						F.G.													

※ Unused wires must be insulated.

※ Encoder case and shield wire must be grounded(F.G.).

※ N.C.: Not Connected.

※ Output cable must not be short-circuited, because Driver IC is used in output circuit.

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■ Connections

- Binary code/Gray code

Color	Resolution	6 division	8 division	10 division	12 division	16 division	20 division	24 division	32 division	40 division	45 division	48 division	64 division	90 division	128 division	180 division	256 division	360 division	512 division	720 division	1024 division
Output wire	Power																				
	White																				+V
	Black																				0V
	Brown																				2^0
	Red																				2^1
	Orange																				2^2
	Yellow	N.C.																			2^3
	Blue	N.C.																			2^4
	Purple	N.C.																			2^5
	Gray	N.C.																			2^6
White/Brown		TP1												N.C.							2^7
White/Red		TP2												N.C.							2^8
White/Orange		EP												N.C.							2^9
Shield wire														F.G.							

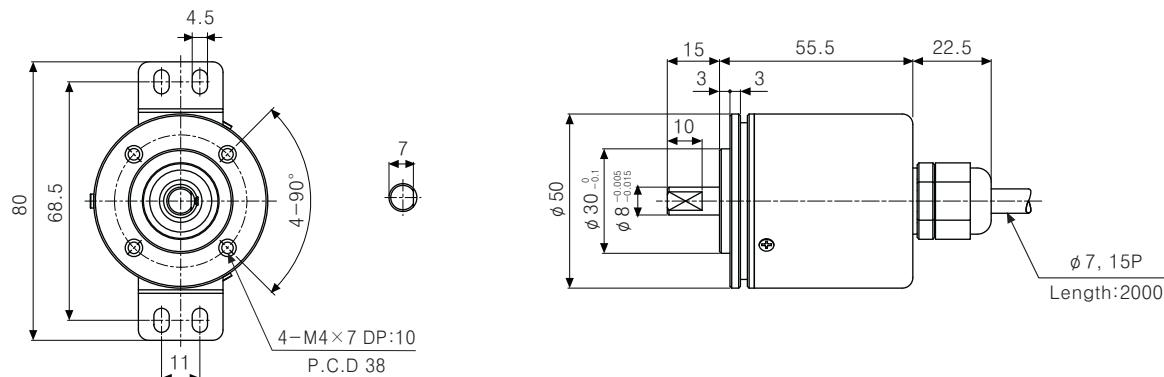
*Unused wires must be insulated.

*Encoder case and shield wire must be grounded(F.G.).

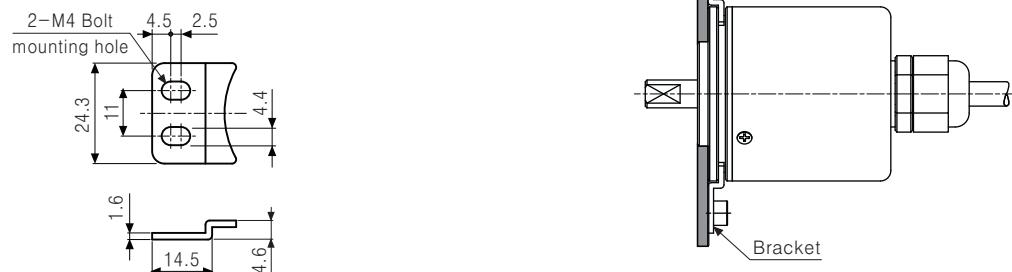
*N.C.: Not Connected.

*Output cable must not be short-circuited, because Driver IC is used in output circuit.

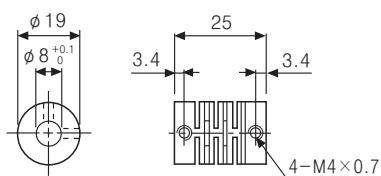
■ Dimensions



● Bracket



● Coupling (EP50S)



(Unit:mm)